

Wednesday 16 January 2008 10.30am to 12.30pm

THEORETICAL PHYSICS I - Solutions

- 1 Question on Lagrangian mechanics – see handwritten solution.
- 2 Question on Hamiltonian mechanics – see handwritten solution.
- 3 (a) The given Lagrangian density is

$$\mathcal{L} = \frac{\hbar}{2i} \left( \Psi \frac{\partial \Psi^*}{\partial t} - \Psi^* \frac{\partial \Psi}{\partial t} \right) - \frac{\hbar^2}{2m} \nabla \Psi \cdot \nabla \Psi^* - V(\mathbf{r}) \Psi \Psi^*$$

Under  $\Psi \rightarrow \Psi e^{-i\alpha}$ ,  $\Psi^* \rightarrow \Psi^* e^{+i\alpha}$ , where  $\alpha$  is a real constant, each term is unchanged, so there is a global phase symmetry.

- (b) The Noether 4-current is

$$J^\mu = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \Psi)} \delta \Psi + \frac{\partial \mathcal{L}}{\partial(\partial_\mu \Psi^*)} \delta \Psi^*$$

where  $\delta \Psi$  is the small change in  $\Psi$ . In this case  $\delta \Psi = -i\alpha \Psi$ , and so, dropping the overall factor of  $\alpha$ ,

$$J^\mu = -i \frac{\partial \mathcal{L}}{\partial(\partial_\mu \Psi)} \Psi + i \frac{\partial \mathcal{L}}{\partial(\partial_\mu \Psi^*)} \Psi^* = (c\rho, \mathbf{J})$$

where

$$\rho = -i \frac{\partial \mathcal{L}}{\partial \dot{\Psi}} \Psi + i \frac{\partial \mathcal{L}}{\partial \dot{\Psi}^*} \Psi^* = \hbar \Psi \Psi^*$$

and

$$\mathbf{J} = -i \frac{\partial \mathcal{L}}{\partial(\nabla \Psi)} \Psi + i \frac{\partial \mathcal{L}}{\partial(\nabla \Psi^*)} \Psi^* = \frac{i\hbar^2}{2m} (\Psi \nabla \Psi^* - \Psi^* \nabla \Psi)$$

The equation of motion (the Schrödinger equation) is

$$i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \Psi + V \Psi$$

so that

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= \hbar \Psi^* \frac{\partial \Psi}{\partial t} + \hbar \Psi \frac{\partial \Psi^*}{\partial t} \\ &= \frac{i\hbar^2}{2m} \Psi^* \nabla^2 \Psi - \frac{i\hbar^2}{2m} \Psi \nabla^2 \Psi^* \\ &= -\nabla \cdot \mathbf{J} \end{aligned}$$

(TURN OVER for continuation of question 3)

which is the conservation equation for the probability density.

(c) The stress-energy tensor is

$$T^{\mu\nu} = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \Psi)} \partial^\nu \Psi + \frac{\partial \mathcal{L}}{\partial(\partial_\mu \Psi^*)} \partial^\nu \Psi^* - g^{\mu\nu} \mathcal{L}$$

i.e.

$$\begin{aligned} T^{00} &= \frac{\partial \mathcal{L}}{\partial \dot{\Psi}} \frac{\partial \Psi}{\partial t} + \frac{\partial \mathcal{L}}{\partial \dot{\Psi}^*} \frac{\partial \Psi^*}{\partial t} - \mathcal{L} \\ &= \frac{\hbar}{2i} \left( -\Psi^* \frac{\partial \Psi}{\partial t} + \Psi \frac{\partial \Psi^*}{\partial t} \right) - \mathcal{L} \\ &= \frac{\hbar^2}{2m} \nabla \Psi \cdot \nabla \Psi^* + V(\mathbf{r}) \Psi \Psi^* \quad (= \mathcal{H}) \end{aligned}$$

and

$$\begin{aligned} T^{j0} &= \frac{\partial \mathcal{L}}{\partial \nabla_j \Psi} \frac{\partial \Psi}{\partial t} + \frac{\partial \mathcal{L}}{\partial \nabla_j \Psi^*} \frac{\partial \Psi^*}{\partial t} \\ &= \frac{-\hbar^2}{2m} \left( \nabla_j \Psi^* \frac{\partial \Psi}{\partial t} + \nabla_j \Psi \frac{\partial \Psi^*}{\partial t} \right) \end{aligned}$$

Similarly (N.B.  $\partial^k = -\nabla_k$ )

$$T^{0k} = \frac{\hbar}{2i} (\Psi^* \nabla_k \Psi - \Psi \nabla_k \Psi^*)$$

and

$$T^{jk} = \frac{\hbar^2}{2m} (\nabla_j \Psi^* \nabla_k \Psi + \nabla_j \Psi \nabla_k \Psi^*) + \delta_{jk} \mathcal{L}$$

(d) From the above equations we have

$$\nabla_j T^{j0} = \frac{-\hbar^2}{2m} \left( \nabla^2 \Psi^* \frac{\partial \Psi}{\partial t} + \nabla^2 \Psi \frac{\partial \Psi^*}{\partial t} + \nabla \Psi^* \cdot \nabla \frac{\partial \Psi}{\partial t} + \nabla \Psi \cdot \nabla \frac{\partial \Psi^*}{\partial t} \right)$$

Using the Schrödinger equation to eliminate  $\nabla^2 \Psi$  and  $\nabla^2 \Psi^*$ , this becomes

$$\nabla_j T^{j0} = \frac{-\hbar^2}{2m} \left( -V \Psi^* \frac{\partial \Psi}{\partial t} - V \Psi \frac{\partial \Psi^*}{\partial t} + \nabla \Psi^* \cdot \nabla \frac{\partial \Psi}{\partial t} + \nabla \Psi \cdot \nabla \frac{\partial \Psi^*}{\partial t} \right) = -\frac{\partial T^{00}}{\partial t}$$

which is the conservation equation for the energy density.

Similarly

$$\begin{aligned} \nabla_j T^{jk} &= \frac{\hbar^2}{2m} \left( \nabla^2 \Psi^* \nabla_k \Psi + \nabla^2 \Psi \nabla_k \Psi^* + \nabla \Psi^* \cdot \nabla (\nabla_k \Psi) + \nabla \Psi \cdot \nabla (\nabla_k \Psi^*) \right) + \nabla_k \mathcal{L} \\ &= \left( V \Psi^* + i\hbar \frac{\partial \Psi^*}{\partial t} \right) \nabla_k \Psi + \left( V \Psi - i\hbar \frac{\partial \Psi}{\partial t} \right) \nabla_k \Psi^* \end{aligned}$$

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$$\begin{aligned}
& + \frac{\hbar}{2i} \left( \nabla_k \Psi \frac{\partial \Psi^*}{\partial t} - \nabla_k \Psi^* \frac{\partial \Psi}{\partial t} + \Psi \nabla_k \frac{\partial \Psi^*}{\partial t} - \Psi^* \nabla_k \frac{\partial \Psi}{\partial t} \right) \\
& - V \Psi \nabla_k \Psi^* - V \Psi^* \nabla_k \Psi - \Psi \Psi^* \nabla_k V \\
= & \frac{\hbar}{2i} \left( -\nabla_k \Psi \frac{\partial \Psi^*}{\partial t} + \nabla_k \Psi^* \frac{\partial \Psi}{\partial t} + \Psi \nabla_k \frac{\partial \Psi^*}{\partial t} - \Psi^* \nabla_k \frac{\partial \Psi}{\partial t} \right) - \Psi \Psi^* \nabla_k V \\
= & -\frac{\partial T^{0k}}{\partial t} + \Psi \Psi^* F_k
\end{aligned}$$

where  $\mathbf{F} = -\nabla V$  is the applied force. Thus

$$\frac{\partial T^{0k}}{\partial t} = -\nabla_j T^{jk} + \Psi \Psi^* F_k$$

which is the expected conservation equation for the momentum density:

$$\text{Rate of change of mom. density} = -(\text{mom. flux}) + (\text{prob. density}) \times \text{force}$$

4 (a) The first term is the free particle action, where  $m$  is the (rest-)mass and  $\tau$  is the proper time. The second term is the interaction between the particle and the field, where  $e$  is the charge,  $A^\mu$  is the 4-vector potential and  $dx^\mu$  is the element of path taken by the particle. The final term is the free field action, where  $F^{\alpha\beta}$  is the field-strength tensor, related to the 4-vector potential by

$$F^{\alpha\beta} = \partial^\alpha A^\beta - \partial^\beta A^\alpha .$$

(b) We have  $S = \int L dt$ ,  $d\tau = dt/\gamma(v)$  (where  $\gamma(v) = 1/\sqrt{1 - v^2/c^2}$  and  $dx^\mu = (dx^\mu/dt)dt$ ), so the Lagrangian for the charged particle is

$$L = -\frac{mc^2}{\gamma(v)} - e(\phi - \mathbf{A} \cdot \mathbf{v})$$

where  $\phi$  is the scalar potential and  $\mathbf{A}$  is the 3-vector potential. The equation of motion is

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \mathbf{v}} \right) = \frac{\partial L}{\partial \mathbf{x}} = \nabla L$$

i.e.

$$\frac{d}{dt}(\gamma m \mathbf{v} + e \mathbf{A}) = -e \nabla \phi + \nabla(\mathbf{A} \cdot \mathbf{v})$$

Now

$$\frac{d\mathbf{A}}{dt} = \frac{\partial \mathbf{A}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{A}$$

and

$$\nabla(\mathbf{A} \cdot \mathbf{v}) - (\mathbf{v} \cdot \nabla) \mathbf{A} = \mathbf{v} \times (\nabla \times \mathbf{A}) = \mathbf{v} \times \mathbf{B}$$

so the equation of motion for the particle is

$$\frac{d}{dt}(\gamma m \mathbf{v} + e \mathbf{A}) = -e \nabla \phi + e \mathbf{v} \times \mathbf{B}$$

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or, since  $\mathbf{E} = -\nabla\phi - \partial\mathbf{A}/\partial t$ ,

$$\frac{d}{dt}(\gamma m \mathbf{v}) = e(\mathbf{E} + \mathbf{v} \times \mathbf{B}).$$

Writing

$$\int A_\mu dx^\mu(t) = \int A_\mu \frac{dx^\mu}{dt} \delta^3(\mathbf{r} - \mathbf{x}(t)) d^3\mathbf{r} dt$$

the part of  $\mathcal{L}$  concerning the e.m. field is

$$\mathcal{L}_{em} = -eA_\mu \frac{dx^\mu}{dt} \delta^3(\mathbf{r} - \mathbf{x}(t)) - \frac{1}{4\mu_0} F_{\alpha\beta} F^{\alpha\beta}$$

Treating  $A_\alpha$  as the field variables, the equation of motion for the e.m. field is

$$\partial_\mu \left( \frac{\partial \mathcal{L}}{\partial (\partial_\mu A_\alpha)} \right) = \frac{\partial \mathcal{L}}{\partial A_\alpha}$$

Writing

$$F_{\alpha\beta} F^{\alpha\beta} = g^{\alpha\mu} g^{\beta\nu} (\partial_\alpha A_\beta - \partial_\beta A_\alpha) (\partial_\mu A_\nu - \partial_\nu A_\mu)$$

we see that the derivative on the l.h.s. has four equal terms, giving

$$\frac{1}{\mu_0} \partial_\mu F^{\mu\alpha} = e \frac{dx^\alpha}{dt} \delta^3(\mathbf{r} - \mathbf{x}(t))$$

The r.h.s. is the 4-current density  $J^\alpha$  due to the moving charged particle. Writing  $J^\mu = (c\rho, \mathbf{J})$ ,  $c = 1/\sqrt{\mu_0\epsilon_0}$  and using the expression given for  $F^{\alpha\beta}$ , this gives

$$\nabla \cdot \mathbf{E} = \rho/\epsilon_0, \quad -\epsilon_0 \partial \mathbf{E} / \partial t + (\nabla \times \mathbf{B}) = \mu_0 \mathbf{J}$$

which are the inhomogeneous Maxwell equations.

(c) A gauge transformation is performed by adding the derivative of a scalar function to the 4-vector potential:

$$A_\alpha \rightarrow A_\alpha + \partial_\alpha f$$

This does not affect  $F_{\alpha\beta}$  since  $\partial_\alpha \partial_\beta f = \partial_\beta \partial_\alpha f$ . The term involving the current density changes by

$$\delta \mathcal{L}_{em} = -(\partial_\alpha f) J^\alpha$$

corresponding to a change in the action

$$\delta S = - \int (\partial_\alpha f) J^\alpha d^4x = \int f \partial_\alpha J^\alpha d^4x - \int \partial_\alpha (f J^\alpha) d^4x$$

The first term on the r.h.s. is zero since the electromagnetic current is conserved,  $\partial_\alpha J^\alpha = 0$ . The second term can be integrated to give a surface term, which contributes at most a constant to  $S$ , which cannot affect the equations of motion.

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(d) A charged scalar field is represented by a complex field  $\varphi$ . Its free-particle Lagrangian density is of the Klein-Gordon form

$$\mathcal{L}_{KG} = (\partial_\mu \varphi)^* (\partial^\mu \varphi) - m^2 \varphi^* \varphi$$

The interaction with an electromagnetic field is included by replacing the derivative  $\partial_\mu$  by the covariant derivative

$$\partial_\mu \rightarrow D_\mu = \partial_\mu + ieA_\mu$$

Thus a scalar field is included by adding the term

$$\mathcal{L}_{KG} = (D_\mu \varphi)^* (D^\mu \varphi) - m^2 \varphi^* \varphi$$

to the Lagrangian density. The symmetry under the gauge transformation  $A_\alpha \rightarrow A_\alpha + \partial_\alpha f$  is preserved by making a compensating phase change in the scalar field:

$$\varphi \rightarrow \varphi e^{-ief}.$$

5 (a) The given Lagrangian density is

$$\begin{aligned} \mathcal{L} &= \frac{1}{2} [(\partial^\mu \varphi)(\partial_\mu \varphi) + a \varphi^2 + b \varphi^4] \\ &= \frac{1}{2} \left[ \left( \frac{\partial \varphi}{\partial t} \right)^2 - (\nabla \varphi)^2 + a \varphi^2 + b \varphi^4 \right] \end{aligned}$$

The equation of motion is

$$\partial_\mu \left( \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} \right) - \frac{\partial \mathcal{L}}{\partial \varphi} = 0$$

i.e.

$$\frac{\partial^2 \varphi}{\partial t^2} - \nabla^2 \varphi - a \varphi - 2b \varphi^3 = 0$$

The momentum density is

$$\pi = \frac{\partial \mathcal{L}}{\partial \dot{\varphi}} = \frac{\partial \varphi}{\partial t}$$

The Hamiltonian density is

$$\mathcal{H} = \pi \dot{\varphi} - \mathcal{L} = \frac{1}{2} \left[ \left( \frac{\partial \varphi}{\partial t} \right)^2 + (\nabla \varphi)^2 - a \varphi^2 - b \varphi^4 \right]$$

For this to be bounded from below we require *either*  $b < 0$  *or* ( $b = 0$  and  $a < 0$ ).

(b) For constant  $\varphi$  we have  $\mathcal{H} = -(a \varphi^2 + b \varphi^4)/2$ . When  $b < 0$ , this has a minimum at  $\varphi_0$  where

$$\frac{\partial \mathcal{H}}{\partial \varphi^2} = -\frac{1}{2}(a + 2b \varphi_0^2) = 0$$

(TURN OVER)

i.e. when  $a > 0$  and

$$\varphi_0 = \pm \sqrt{\frac{-a}{2b}}$$

The system must choose either the  $+$  or  $-$  root, so the symmetry is spontaneously broken when  $a > 0$  and  $b < 0$ . The minimum energy density is then

$$\mathcal{H}_0 = \frac{1}{2} \frac{a^2}{2b} - \frac{b}{2} \left( \frac{-a}{2b} \right)^2 = \frac{a^2}{8b} < 0$$

(c) Write  $\varphi = \varphi_0 + \chi$ . Then

$$\begin{aligned} a\varphi^2 + b\varphi^4 &= a(\varphi_0^2 + 2\varphi_0\chi + \chi^2) + b(\varphi_0^4 + 4\varphi_0^3\chi + 6\varphi_0^2\chi^2 + 4\varphi_0\chi^3 + \chi^4) \\ &= a\varphi_0^2 + b\varphi_0^4 + 2\varphi_0(\chi(a + 2b\varphi_0^2) + \chi^2(a + 6b\varphi_0^2) + \mathcal{O}(\chi^3)) \\ &= a\varphi_0^2 + b\varphi_0^4 - 2a\chi^2 + \mathcal{O}(\chi^3) \end{aligned}$$

Hence the Lagrangian density becomes

$$\mathcal{L} = \frac{1}{2} [(\partial^\mu \chi)(\partial_\mu \chi) - 2a\chi^2 + \mathcal{O}(\chi^3)] - \mathcal{H}_0$$

and the equation of motion for  $\chi$  is

$$\frac{\partial^2 \chi}{\partial t^2} - \nabla^2 \chi + 2a\chi = \mathcal{O}(\chi^2)$$

For  $\chi$  small the r.h.s. is negligible and the dispersion relation, obtained by substituting e.g.  $\chi = \cos(kx - \omega t)$ , is  $-\omega^2 + k^2 + 2a = 0$ , i.e.

$$\omega = \sqrt{k^2 + 2a}$$

which corresponds to a real mass  $m = \sqrt{2a}$  (in natural units) for the quanta of the field.

6 Question on Green's functions – see handwritten solution.

END OF PAPER

The co-ordinate system we will use is as follows: the mass  $m$  is at  $(x, y)$ , the pendulum makes an angle  $\phi$  to the downward vertical, the centre of the cylinder is at  $(X, R)$  and the cylinder rotates at angular velocity  $\dot{\theta}$  such that  $\dot{X} = R\dot{\theta}$ . Then,  $x = X + c \sin \phi$ ,  $y = R - c \cos \phi$  and  $\dot{x} = R\dot{\theta} + c\dot{\phi} \cos \phi$ ,  $\dot{y} = c\dot{\phi} \sin \phi$ . The kinetic and rotational energies of the cylinder are both  $MR^2\dot{\theta}^2/2$ , and the potential energy of the mass  $m$  is  $-mga \cos \phi$ . The Lagrangian is therefore

$$L = \frac{m}{2} \left( R^2\dot{\theta}^2 + c^2\dot{\phi}^2 + 2cR\dot{\theta}\dot{\phi} \cos \phi \right) + MR^2\dot{\theta}^2 + mga \cos \phi$$

and the Euler-Lagrange equations are

$$\begin{aligned} mc^2\ddot{\phi} + mcR\ddot{\theta} \cos \phi - mcR\dot{\theta}\dot{\phi} \sin \phi + mgc \sin \phi &= 0 \\ (m + 2M)R^2\ddot{\theta} + mcR\dot{\phi} \cos \phi &= \kappa \end{aligned}$$

for some constant  $\kappa$  (as  $\frac{\partial L}{\partial \theta} = 0$  so  $\frac{\partial L}{\partial \theta}$  is constant). Rearranging the second equation and differentiating,

$$\ddot{\theta} = \frac{mcR}{R^2(m + 2M)} \left( -\ddot{\phi} \cos \phi + \dot{\phi}^2 \sin \phi \right).$$

Substituting this into the equation of motion for  $\theta$ ,

$$\begin{aligned} \left( mc^2 - \frac{(mcR)^2}{R^2(m + 2M)} \cos^2 \phi \right) \ddot{\phi} + \frac{2(mcR)^2}{R^2(m + 2M)} \dot{\phi}^2 \cos \phi \sin \phi \\ - \frac{mcR\kappa}{R^2(m + 2M)} \dot{\phi} \sin \phi + mgc \sin \phi = 0 \end{aligned}$$

For small oscillations,  $\phi \sim \epsilon \sin \omega t$ ,  $\dot{\phi} \sim \epsilon \omega \cos \omega t$ ,  $\cos \phi \sim 1$  and we can ignore terms proportional to  $\dot{\phi}^2$  and  $\dot{\phi} \sin \phi$  which are second order in  $\epsilon$ . The above equation then becomes

$$\frac{2Mc}{m + 2M} \ddot{\phi} + g \sin \phi = 0$$

This is the equation of motion for a pendulum of length  $\lambda = 2Mc/(m + 2M)$ .

The Hamiltonian is

$$\begin{aligned} H &= p_\theta \dot{\theta} + p_\phi \dot{\phi} - L \\ &= \frac{1}{2} mc^2 \dot{\phi}^2 + \frac{1}{2} mR^2 \dot{\theta}^2 + MR^2 \dot{\theta}^2 + mcR\dot{\theta}\dot{\phi} \cos \phi - mgc \cos \phi \end{aligned}$$

which is independent of time and therefore conserved. Initially  $\phi = 0$ ,  $\dot{X} = R\dot{\theta} = V$ , and  $\dot{x} = V + c\dot{\phi} = 0$  so  $\dot{\phi} = -V/c$ . Substituting this into the Hamiltonian, we see that the initial energy of the system is  $E = MV^2 - mgc$ . We also found earlier that the angular momentum is conserved; in terms of  $V$ , the initial angular momentum is  $\kappa = 2MRV$ . Equating the initial energy of the system to the Hamiltonian, substituting the previously derived expressions for  $\dot{\theta}$  and  $\kappa$ , and rearranging we find

$$\frac{1}{2} mc^2 \left( 1 - \frac{m \cos^2 \phi}{m + 2M} \right) \dot{\phi}^2 = \frac{mM}{m + 2M} V^2 - mgc(1 - \cos \phi)$$

Advantages of the Hamiltonian formulation over the Lagrangian formulation include:

- The Lagrangian formulation leads to  $N$  second order differential equations while the Hamiltonian formulation leads to  $2N$  first order differential equations, which may be easier to solve.
- The  $q_i$  in the Lagrangian formulation must be position co-ordinates, whereas in the Hamiltonian formulation the  $q_i$  and  $p_i$  are on an equal footing and the  $q_i$  need not be position co-ordinates. This also means that canonical transformations with mixed momenta and position can be used to greatly simplify Hamilton's equations. (This will be illustrated later in this question)
- The Hamiltonian formulation can lead to easily identifiable constants of motion (for example, if  $H$  is independent of  $t$  then energy is conserved). The presence of a conserved quantity immediately simplifies Hamilton's equations, whereas no immediate simplification would occur in the Lagrangian formulation.
- There is a simple relationship between the (classical) Hamiltonian formulation and quantum mechanics.

Starting from the Hamiltonian

$$H(q, p, t) = p\dot{q} - L(q, \dot{q}, t)$$

we find the differential  $dH$  and substitute using the Euler-Lagrange equation:

$$\begin{aligned} dH &= \frac{\partial H}{\partial p} dp + \frac{\partial H}{\partial q} dq + \frac{\partial H}{\partial t} dt \\ &= p d\dot{q} + \dot{q} dp - \frac{\partial L}{\partial q} dq - \frac{\partial L}{\partial \dot{q}} d\dot{q} - \frac{\partial L}{\partial t} dt \\ &= \dot{q} dp - \dot{p} dq - \frac{\partial L}{\partial t} dt. \end{aligned}$$

Comparing the first and third lines therefore gives Hamilton's equations,

$$\dot{q} = \frac{\partial H}{\partial p}, \quad -\dot{p} = \frac{\partial H}{\partial q}, \quad \frac{\partial H}{\partial t} = -\frac{\partial L}{\partial t}.$$

We then write the first two of Hamilton's equations in matrix form,

$$\begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial q} \\ \frac{\partial H}{\partial p} \end{pmatrix}$$

and note that our co-ordinate transformation means that

$$\begin{pmatrix} \dot{Q} \\ \dot{P} \end{pmatrix} = \begin{pmatrix} \frac{\partial Q}{\partial q} & \frac{\partial Q}{\partial p} \\ \frac{\partial P}{\partial q} & \frac{\partial P}{\partial p} \end{pmatrix} \begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix}, \quad \begin{pmatrix} \frac{\partial H}{\partial q} \\ \frac{\partial H}{\partial p} \end{pmatrix} = \begin{pmatrix} \frac{\partial Q}{\partial q} & \frac{\partial P}{\partial q} \\ \frac{\partial Q}{\partial p} & \frac{\partial P}{\partial p} \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial Q} \\ \frac{\partial H}{\partial P} \end{pmatrix}$$



and so

$$\begin{pmatrix} \dot{Q} \\ \dot{P} \end{pmatrix} = \begin{pmatrix} \frac{\partial Q}{\partial q} & \frac{\partial Q}{\partial p} \\ \frac{\partial P}{\partial q} & \frac{\partial P}{\partial p} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \frac{\partial Q}{\partial q} & \frac{\partial P}{\partial q} \\ \frac{\partial Q}{\partial p} & \frac{\partial P}{\partial p} \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial Q} \\ \frac{\partial H}{\partial P} \end{pmatrix}.$$

Performing one of the matrix multiplications, we then note that for Hamilton's equations to be obeyed in the  $Q, P$  co-ordinates we require

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} -\frac{\partial Q}{\partial p} & \frac{\partial Q}{\partial q} \\ -\frac{\partial P}{\partial p} & \frac{\partial P}{\partial q} \end{pmatrix} \begin{pmatrix} \frac{\partial Q}{\partial q} & \frac{\partial P}{\partial q} \\ \frac{\partial Q}{\partial p} & \frac{\partial P}{\partial p} \end{pmatrix}.$$

The 2,1 element of this matrix equation then tells us that

$$-1 = -\frac{\partial P}{\partial p} \frac{\partial Q}{\partial q} + \frac{\partial P}{\partial q} \frac{\partial Q}{\partial p} = -\{Q, P\}_{q,p}$$

as required.

For the co-ordinate transformation given in the question,

$$\frac{\partial Q}{\partial q} = \frac{m\omega p}{p^2 + (m\omega q)^2}, \quad \frac{\partial Q}{\partial p} = \frac{-m\omega q}{p^2 + (m\omega q)^2}, \quad \frac{\partial P}{\partial q} = m\omega q, \quad \frac{\partial P}{\partial p} = \frac{p}{m\omega}$$

from which it follows that the above Poisson bracket holds. Now, the inverse co-ordinate transform is

$$\begin{aligned} p &= \sqrt{2m\omega P} \cos Q \\ q &= \frac{\sqrt{2m\omega P}}{m\omega} \sin Q \end{aligned}$$

so in the  $Q, P$  co-ordinate system the Hamiltonian for the simple harmonic oscillator is  $H = \omega P$ . Hamilton's equations are then

$$\dot{Q} = \frac{\partial H}{\partial P} = \omega, \quad -\dot{P} = \frac{\partial H}{\partial Q} = 0$$

the solutions to which are

$$Q = \omega t + \alpha, \quad P = \beta$$

for some constants  $\alpha, \beta$ . Finally, we rewrite this solution in the  $q, p$  co-ordinate system:

$$q = \frac{\sqrt{2m\omega\beta}}{m\omega} \cos(\omega t + \alpha), \quad p = \sqrt{2m\omega\beta} \sin(\omega t + \alpha)$$

which is the familiar solution for a simple harmonic oscillator.

The Green's function (by definition) satisfies the equation

$$\left(i\hbar \frac{\partial}{\partial t} + \frac{\hbar^2}{2m} \nabla^2\right) G(\mathbf{r}, \mathbf{r}'; t, t') = \delta^3(\mathbf{r} - \mathbf{r}') \delta(t - t')$$

The Fourier transform of the right hand side is 1. To Fourier transform the left hand side, we will change variables to  $\tau = t - t'$ , so

$$i\hbar \int d\tau e^{iz\tau/\hbar} \frac{\partial G(\tau)}{\partial t} = -i\hbar \int \frac{iz}{\hbar} e^{iz\tau/\hbar} G(\tau) d\tau = zG(\mathbf{r}, \mathbf{r}'; z)$$

where we have integrated by parts, noting that the boundary term is zero. Thus,

$$\left(z + \frac{\hbar^2}{2m} \nabla^2\right) G(\mathbf{r}, \mathbf{r}'; z) = \delta^3(\mathbf{r} - \mathbf{r}')$$

Next, we note that  $\nabla^2 \leftrightarrow -k^2$  under Fourier transformation and let  $\mathbf{p} = \mathbf{r} - \mathbf{r}'$  so that

$$\begin{aligned} G(\mathbf{r}, \mathbf{r}'; z) &= \int \frac{d\mathbf{k}}{(2\pi)^3} \frac{e^{i\mathbf{k}\cdot(\mathbf{r}-\mathbf{r}')}}{z - \hbar^2 k^2/2m} \\ &= \frac{1}{(2\pi)^3} \int k^2 dk \sin\theta d\theta d\phi \frac{e^{i\mathbf{k}\cdot\mathbf{p}}}{z - \hbar^2 k^2/2m} \\ &= \frac{1}{(2\pi)^2} \int_0^\infty \frac{k^2 dk}{z - \hbar^2 k^2/2m} \int_0^\pi d\theta \sin\theta e^{ikp \cos\theta} \\ &= \frac{1}{(2\pi)^2} \int_0^\infty \frac{k^2 dk}{z - \hbar^2 k^2/2m} \frac{e^{ikp} - e^{-ikp}}{ikp} \\ &= \frac{2m}{i(2\pi)^2 p \hbar^2} \int_{-\infty}^\infty \frac{k e^{ikp}}{2mz/\hbar^2 - k^2} dk \end{aligned}$$

where the symmetry properties of the  $k$  integrand were used to change the range of  $k$  integration. The integrand has poles at  $k = \pm\sqrt{2mz}/\hbar$ . We first consider the case  $z = E + i\epsilon$ , which has poles at  $k_{1,2} = \pm(\sqrt{2m}/\hbar)E^{1/2}e^{i\epsilon/2}$  (because  $(E^{1/2}e^{i\epsilon/2})^2 = Ee^{i\epsilon} \simeq E + i\epsilon$  when  $\epsilon$  is small). We will close the contour of integration with a semi-circle in the upper half plane; the contribution from the semi-circular arc vanishes due to Jordan's lemma. Only the pole at  $k_1$  is enclosed which has residue  $-e^{ik_1 p}/2$ , using l'Hôpital's rule. When  $z = E - i\epsilon$  the poles move to  $k_{1,2} = \pm(\sqrt{2m}/\hbar)E^{1/2}e^{-i\epsilon/2}$  and the pole enclosed by the contour is the one at  $k_2 = -(\sqrt{2m}/\hbar)E^{1/2}e^{-i\epsilon/2}$  with residue  $-e^{ik_2 p}$ . (For the  $E < 0$  cases, we just need to replace  $\sqrt{E}$  by  $i\sqrt{E}$ ). We multiply the residues by  $2\pi i$  to arrive at the required integrals, and then use the definition of  $\Delta G$  given in the question along with the integrals for the  $E > 0$  cases to arrive at

$$\Delta G = -2\pi i \frac{2m}{\hbar^2} \frac{\sin\left(\sqrt{2mE}|\mathbf{r} - \mathbf{r}'|/\hbar\right)}{4\pi^2|\mathbf{r} - \mathbf{r}'|} \Theta(E)$$

For a particle in free space,  $E = \hbar^2 k^2 / 2m$  so  $dk/dE = \sqrt{2m} / 2\hbar\sqrt{E}$ . Each state in  $k$ -space occupies a volume  $(2\pi)^3$ , so the number in a sphere of radius  $k$  is  $n = 4\pi k^3 / 3(2\pi)^3$ . Therefore, the density of states is

$$\begin{aligned} \frac{dn}{dE} &= \frac{4\pi k^2}{(2\pi)^3} \frac{dk}{dE} \\ &= \frac{m}{2\pi^2 \hbar^3} \sqrt{2mE}. \end{aligned}$$

Noting that the limit of  $\sin(x)/x$  as  $x$  tends to zero is 1, comparing this to the earlier equation for  $\Delta G$  shows that in this case

$$\rho(E) = \lim_{\mathbf{r} \rightarrow \mathbf{r}'} \frac{\Delta G(\mathbf{r}, \mathbf{r}'; E)}{-2\pi i}.$$

For the last part we again use  $G = 1/(z - E_n)$ , so

$$G = \sum_n \frac{|n\rangle\langle n|}{z - E_n}$$

because the eigenstates  $|n\rangle$  form a complete set, and

$$\begin{aligned} G(\mathbf{r}, \mathbf{r}'; z) \equiv \langle \mathbf{r} | G | \mathbf{r}' \rangle &= \sum_n \frac{\langle \mathbf{r} | n \rangle \langle n | \mathbf{r}' \rangle}{z - E_n} \\ &= \sum_n \frac{\phi_n(\mathbf{r}) \phi_n^*(\mathbf{r}')}{z - E_n} \end{aligned}$$

Writing  $z = E \pm is$ ,

$$G^\pm(\mathbf{r}, \mathbf{r}'; z) = \sum_n \frac{\phi_n(\mathbf{r}) \phi_n^*(\mathbf{r}')}{(E - E_n) \pm is}.$$

Using the identity given in the question,

$$\Delta G(\mathbf{r}, \mathbf{r}; E) = -2\pi i \sum_n \phi_n(\mathbf{r}) \phi_n^*(\mathbf{r}') \delta(E - E_n)$$

and so

$$\rho(E) = \lim_{\mathbf{r} \rightarrow \mathbf{r}'} \frac{\Delta G(\mathbf{r}, \mathbf{r}'; E)}{-2\pi i}$$

as required.